## **Energy Harvesting Eel**

DARPA Program: BAA-97-44, Energy Harvesting

DARPA Program Manager: Dr. Robert Nowak
ONR Program Manager: Dr. Tom Curtin

April 13, 2000

# Future Objective

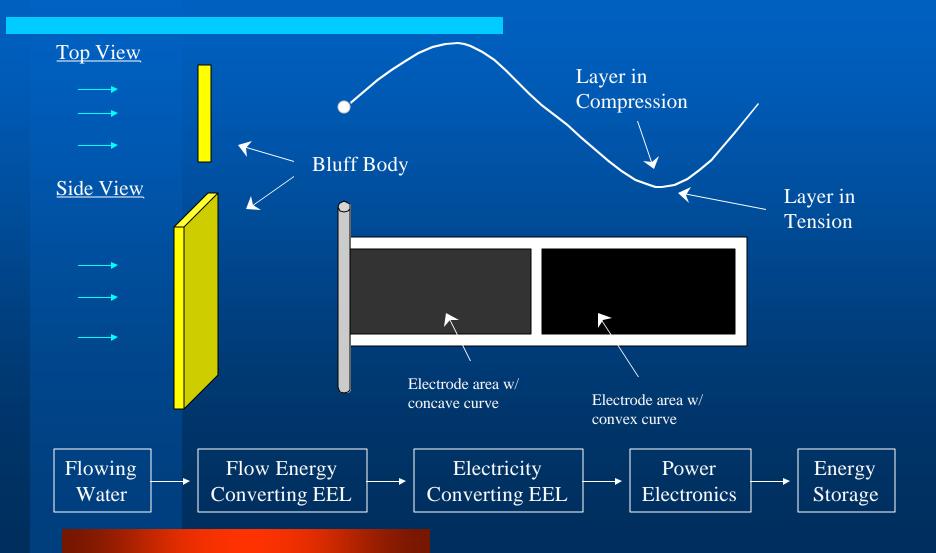
### Team Members

- Ocean Power Technologies: Program Management, Systems, Power Extraction, Bias Supply
- Autonomous Undersea Systems Institute: Eel-Water Interaction, Electronics, Microprocessor
- Cambridge Advanced Technologies & Simulation: Numerical Modeling of Eel-Water interaction, formation of Eel design tool
- Princeton University: Hydrodynamics of Eel and Bluff Body, Flow Testing and Visualization
- Penn State University: Materials Research and Development
- Measurement Specialties Inc.: Material and Eel Fabrication, Materials Expertise

## Program Approach

- The Eel utilizes a regular pattern of bending and unbending of a piezoelectric or electrostrictive material caused by moving water and converts it to electrical power.
- By inserting a vortex generator upstream of the Eel-like device a vortex street is generated.
- The forces generated by the traveling vortices on either side of the Eel produce a forcing field on the body. Present simulations are underway to reveal the optimum cross sectional Eel geometry based off of these forcing fields.
- The Eel currently is made up of piezoelectric PVDF, electrostrictive PVDF: TrFE copolymer is being concurrently bench tested. It is planned that the copolymer will be integrated into the system during the upcoming program year.

### Illustration of Program Approach

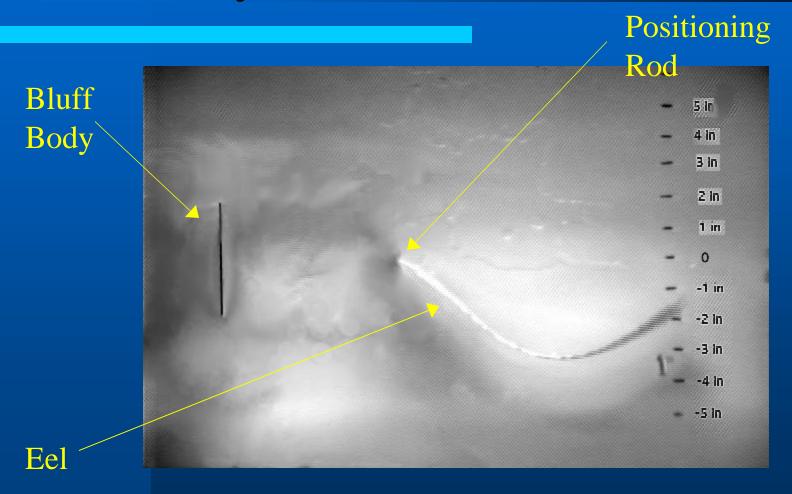


# Program Goals

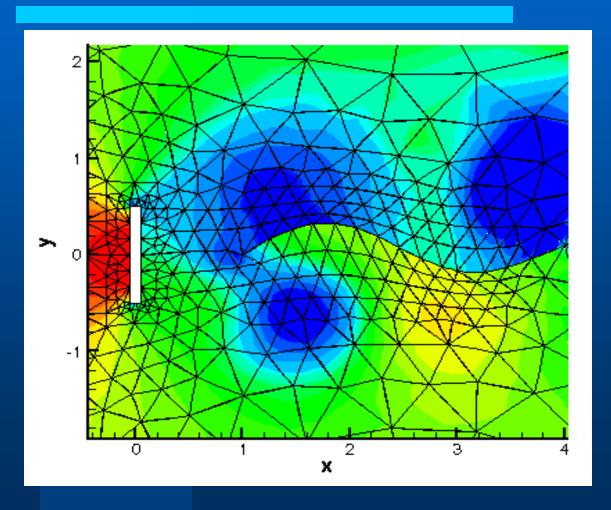
Flow Velocity (m/s)	Power @60cm <sup>2</sup> (Watts)	Power @310cm <sup>2</sup> (Watts)
1.5	2.03	10.45
1	0.60	3.10
0.5	0.075	0.39
0.25	0.010	0.05

Based on experimental results a flow energy capture efficiency of 50%, a generating module efficiency of 50%, and a power electronics efficiency of 80% is assumed above. Cross sectional areas of 60 cm<sup>2</sup> (3"x3") and 310 cm<sup>2</sup> (4"x12") are used in the table.

## Eel Body in flow tank at .5 m/s



# NEKTAR Fluid-Solid Interaction Modeling



A specific Eel length, bluff body width, and flow speed results in a forcing file.

The Eel moves in relation to this forcing field based on the inputs E, I, and m.
The resulting behavior is graphically demonstrated.

# NEKTAR Fluid-Solid Interaction Modeling

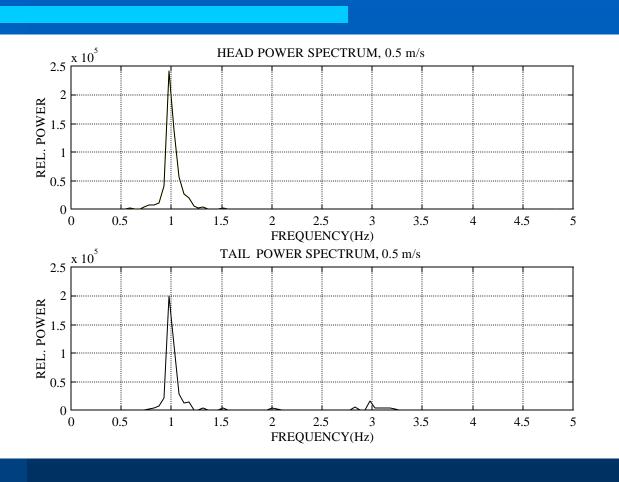
NEKTAR has been developed and run under several different Reynolds numbers, bluff body widths, and Eel lengths to produce a forcing file database.

Using the database, specific Eel characteristics for any specified flow condition will be inserted and the forcing files produce the resulting Eel motion. The input characteristics include:

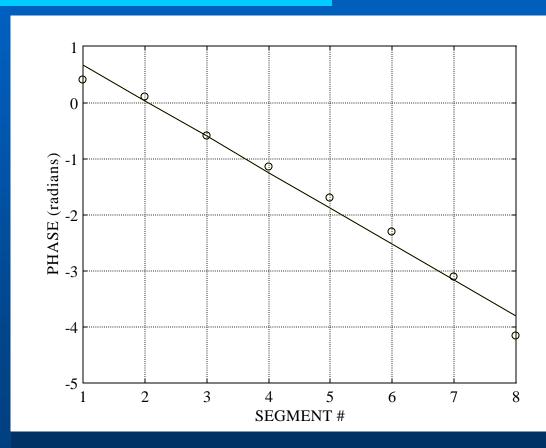
- 1) Modulus
- 2) Moment of Inertia
- 3) Mass

- 4) Flow Speed
- 5) Bluff Body Width
- 6) Eel Length

# Power Spectrum of Electroded Eel

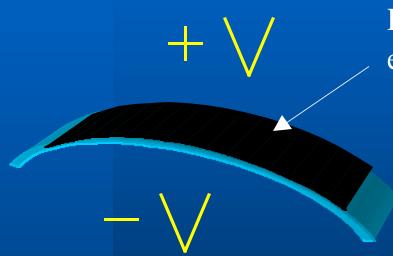


# Eel Motion corresponds to Traveling Wave



Angle of Fundamental vs. Segment # at 0.5 m/s

# Mechanical to Electrical Power Conversion (PVDF:TrFE)



Printed electrode

Generating material parameters: Y, •

 $d_{31}$ =120 pC/N @ 40 MV/m\*  $k_{31}^2 \sim 5^{1/4}\%$  @ 40 MV/m

### Figures of Merit

$$d_{31} = \varepsilon/Y E_B$$
  
 $k_{31}^2 \equiv c d_{31}^2 Y/\varepsilon = c \varepsilon/Y E_B^2$ 

:. efficiency of 50 % with switched resonant

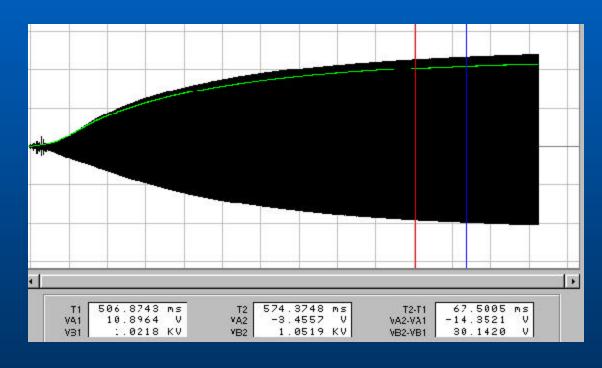
\*40 MV/m =1000 V across 25 mm

# Low Power DC to High Voltage DC Converter

•Elapsed time ~ .5 seconds

•DC voltage gain: 3 Volts to ~ 1kV

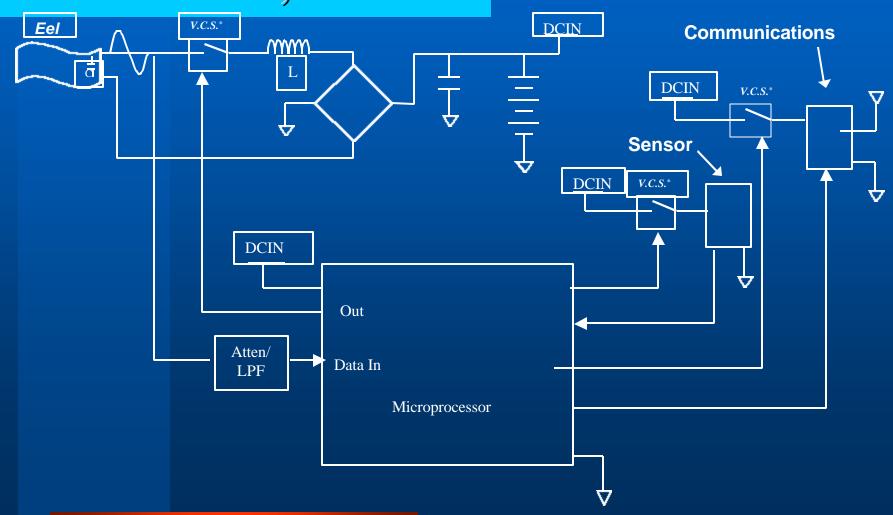
•Power required: 12 mW



Green: Bias Voltage on Capacitor

Black: Voltage on Oscillator (Low Voltage end of transformer)

# Eel System w/ Battery Charging, Sensor, and Communications



# How do we stack up?

**Complete System Efficiency** = 20 % vs. < 16 % for rotary turbine

#### **Advantages over Turbine:**

- Broadband efficiency curve vs. steep turbine curve
- Operates well in low frequency environments
- no additional losses in gearing

Small in size ~ 4 in<sup>3</sup> Light weight ~ 1/4 lb

Easily scalable

Modular design

# Advantages of Eel System for Energy Harvesting

**Scalable** Modular **Environmentally Friendly Easily Deployable** Autonomous Reliable Can operate at low flow energy levels Intrinsically inexpensive Suited for covert operation Structure suitable for mounting electronics and sensors

## **Applications**

#### **MILITARY APPLICATIONS**

- 1) Long Term Sonar Buoys
- 2) power various unattended sensors

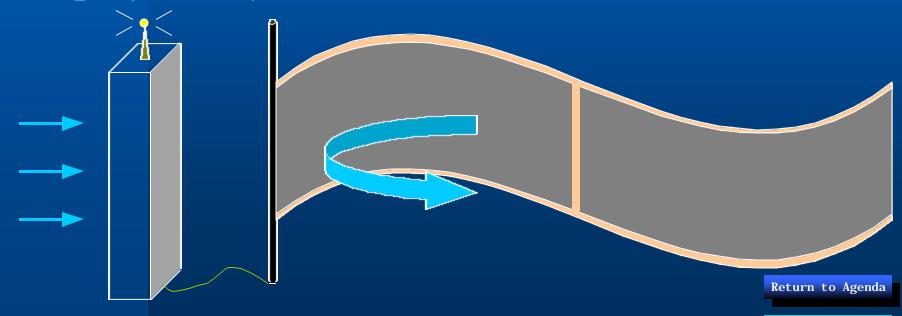
#### **COMMERCIAL APPLICATIONS**

- 1) Auxiliary power for sensing and communicating in natural gas and water transmission lines
- 2) Self powered and automatic communicating for oceanographic sensors
- 3) Short range RF communications
- 4) Capturing horizontal wave energy in a wave powered system

short range radio link = 50 mW of required power

### The Future of the Eel

The upcoming option will be used to fully integrate the Energy Harvesting Eel into a deployable system.



Next Presentation